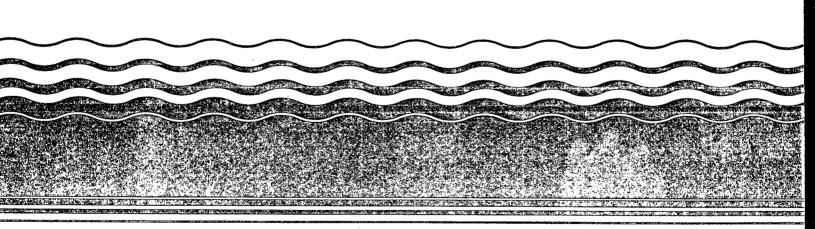


Compendium of ERT Soil Sampling and Surface Geophsics Procedures



....

COMPENDIUM OF ERT SOIL SAMPLING AND SURFACE GEOPHYSICS PROCEDURES

Sampling Equipment Decontamination

Soil Sampling

Soil Gas Sampling

General Surface Geophysics

Interim Final

Environmental Response Team **Emergency Response Division**

Office of Emergency and Remedial Response U.S. Environmental Protection Agency Washington, DC 20460



Notice

This document has been reviewed in accordance with U.S. Environmental Protection Agency policy and approved for publication. Mention of trade names or commercial products does not constitute endorsement or recommendation for use.

The policies and procedures established in this document are intended solely for the guidance of government personnel for use in the Superfund Removal Program. They are not intended, and cannot be relied upon, to create any rights, substantive or procedural, enforceable by any party in litigation with the United States. The Agency reserves the right to act at variance with these policies and procedures and to change them at any time without public notice.

Depending on circumstances and needs, it may not be possible or appropriate to follow these procedures exactly in all situations due to site conditions, equipment limitations, and limitations of the standard procedures. Whenever these procedures cannot be followed as written, they may be used as general guidance with any and all modifications fully documented in either QA Plans, Sampling Plans, or final reports of results.

Each Standard Operating Procedure in this compendium contains a discussion on quality assurance/quality control (QA/QC). For more information on QA/QC objectives and requirements, refer to the *Quality Assurance/Quality Control Guidance for Removal Activities*, OSWER directive 9360.4-01, EPA/540/G-90/004.

Questions, comments, and recommendations are welcomed regarding the Compendium of ERT Soil Sampling and Surface Geophysics Procedures. Send remarks to:

Mr. William A. Coakley
Removal Program QA Coordinator
U.S. EPA - ERT
Raritan Depot - Building 18, MS-101
2890 Woodbridge Avenue
Edison, NJ 08837-3679

For additional copies of the Compendium of ERT Soil Sampling and Surface Geophysics Procedures, please contact:

National Technical Information Service (NTIS)
U.S. Department of Commerce
5285 Port Royal Road
Springfield, VA 22161
(703) 487-4600

Table of Contents

<u>Secti</u>	on		Page
1.0	SAM	PLING EQUIPMENT DECONTAMINATION: SOP #2006	
	1.1 1.2 1.3 1.4 1.5 1.6 1.7	Scope and Application Method Summary Sample Preservation, Containers, Handling, and Storage Interferences and Potential Problems Equipment/Apparatus Reagents Procedures	1 1 1 1 1 2 2
		1.7.1 Decontamination Methods1.7.2 Field Sampling Equipment Cleaning Procedures	2 3
	1.8 1.9 1.10 1.11	Calculations Quality Assurance/Quality Control Data Validation Health and Safety	3 3 4 4
2.0	SOIL	SAMPLING: SOP #2012	
	2.1 2.2 2.3 2.4 2.5 2.6 2.7	Scope and Application Method Summary Sample Preservation, Containers, Handling, and Storage Interferences and Potential Problems Equipment/Apparatus Reagents Procedures	5 5 5 5 5 5 6
		2.7.1 Preparation 2.7.2 Sample Collection	6 6
	2.8 2.9 2.10 2.11	Calculations Quality Assurance/Quality Control Data Validation Health and Safety	9 9 9 9
3.0	SOIL	GAS SAMPLING: SOP #2149	
	3.1 3.2 3.3	Scope and Application Method Summary Sample Preservation, Containers, Handling, and Storage	11 11 11
		3.3.1 Tedlar Bag 3.3.2 Tenax Tube 3.3.3 SUMMA Canister	11 11

Section			Page
3.4	Interf	Gerences and Potential Problem	12
	3.4.1	HNU Measurements 12	
	3.4.2	Factors Affecting Organic Concentrations in Soil Gas	12
	3.4.3	Soil Probe Clogging	12
	3.4.4	Underground Utilities	12
3.5	Equip	oment/Apparatus	12
	3.5.1	Slam Bar Method	12
	3.5.2	Power Hammer Method	13
3.6	Reage	ents	13
3.7	Proce	edures	13
	3.7.1	Soil Gas Well Installation	13
	3.7.2	Screening with Field Instruments	14
	3.7.3	Tedlar Bag Sampling	14
	3.7.4	Tenax Tube Sampling	14
	3.7.5	SUMMA Canister Sampling	16
3.8	S Calcu	ılations	16
	3.8.1	Field Screening Instruments	16
	3.8.2	Photovac GC Analysis	16
3.9	Quali	ity Assurance/Quality Control	16
	3.9.1	Field Instrument Calibration	16
	3.9.2	Gilian Model HFS113A Air Sampling Pump Calibration	16
	3.9.3	Sample Probe Contamination	16
	3.9.4	Sample Train Contamination	16
	3.9.5	Field Blank	16
	3.9.6	Trip Standard	16
	3.9.7		17
	3.9.8	SUMMA Canister Check	17
	3.9.9	Options	17
3.1	0 Data	Validation	17
3.1	1 Healt	th and Safety	17

Ċ

Section	<u>n</u>			Page
4.0	SOIL	SAMPL	ING AND SURFACE GEOPHYSICS: SOP #2159	
	4.1	Scope	and Application	19
	4.2	Metho	od Summary	19
		4.2.1	Magnetics	19
		4.2.2	Electromagnetics	20
		4.2.3	Electrical Resistivity	20
		4.2.4	Seismic	21
		4.2.5	Ground Penetrating Radar	22
•	4.3		le Preservation, Containers, Handling and Storage	23
	4.4		erences and Potential Problems	23
	4.5	Equip	ment/Apparatus	24
		4.5.1	Magnetics	24
		4.5.2	Electromagnetics	24
		4.5.3	Electrical Resistivity	24
		4.5.4	Seismic	24
		4.5.5	Ground Penetrating Radar	24
	4.6	Reage		24
	4.7	Proced		24
	4.8	Calcul		24
	4.9		y Assurance/Quality Control	24
	4.10		Validation	24
	4.11	Health	and Safety	24
APPE	NDIX A	A - Figure	es .	25
APPE	NDIX B	- HNU	Field Protocol	29
REFE	RENCE	S		22

List of Exhibits

Exhibit		SOP	Page
Table 1:	Recommended Solvent Rinse for Soluble Contaminants	#2006	4
Figure 1:	Sampling Augers	#2012	26
Figure 2:	Sampling Trier	#2012	27
Figure 3:	Sampling Train Schematic	#2149	28

Acknowledgments

Preparation of this document was directed by William A. Coakley, the Removal Program QA Coordinator of the Environmental Response Team, Emergency Response Division. Additional support was provided under U.S. EPA contract #68-03-3482 and U.S. EPA contract #68-WO-0036.

• !

1.0 SAMPLING EQUIPMENT DECONTAMINATION: SOP #2006

1.1 SCOPE AND APPLICATION

This Standard Operating Procedure (SOP) describes methods used for preventing or reducing cross-contamination, and provides general guidelines for sampling equipment decontamination procedures at a hazardous waste site. Preventing or minimizing cross-contamination in sampled media and in samples is important for preventing the introduction of error into sampling results and for protecting the health and safety of site personnel.

Removing or neutralizing contaminants that have accumulated on sampling equipment ensures protection of personnel from permeating substances, reduces or eliminates transfer of contaminants to clean areas, prevents the mixing of incompatible substances, and minimizes the likelihood of sample cross-contamination.

1.2 METHOD SUMMARY

Contaminants can be physically removed from equipment, or deactivated by sterilization or disinfection. Gross contamination of equipment requires physical decontamination, including abrasive and non-abrasive methods. These include the use of brushes, air and wet blasting, and high-pressure water cleaning, followed by a wash/rinse process using appropriate cleaning solutions. Use of a solvent rinse is required when organic contamination is present.

1.3 SAMPLE PRESERVATION, CONTAINERS, HANDLING, AND STORAGE

This section is not applicable to this SOP.

1.4 INTERFERENCES AND POTENTIAL PROBLEMS

 The use of distilled/deionized water commonly available from commercial vendors may be acceptable for decontamination of sampling equipment provided that it has been verified by laboratory analysis to be analyte free.

- An untreated potable water supply is not an acceptable substitute for tap water. Tap water may be used from any municipal water treatment system for mixing of decontamination solutions.
- Acids and solvents utilized in the decontamination sequence pose the health and safety risks of inhalation or skin contact, and raise shipping concerns of permeation or degradation.
- The site work plan must address disposal of the spent decontamination solutions.
- Several procedures can be established to minimize contact with waste and the potential for contamination. For example:
 - Stress work practices that minimize contact with hazardous substances.
 - Use remote sampling, handling, and container-opening techniques when appropriate.
 - Cover monitoring and sampling equipment with protective material to minimize contamination.
 - Use disposable outer garments and disposable sampling equipment when appropriate.

1.5 EQUIPMENT/APPARATUS

- appropriate personal protective clothing
- non-phosphate detergent
- selected solvents
- long-handled brushes
- drop cloths/plastic sheeting
- trash container
- paper towels
- galvanized tubs or buckets
- tap water

- distilled/deionized water
- metal/plastic containers for storage and disposal of contaminated wash solutions
- pressurized sprayers for tap and deionized/distilled water
- sprayers for solvents
- trash bags
- aluminum foil
- safety glasses or splash shield
- emergency eyewash bottle

1.6 REAGENTS

There are no reagents used in this procedure aside from the actual decontamination solutions and solvents. In general, the following solvents are utilized for decontamination purposes:

- 10% nitric acid(1)
- acetone (pesticide grade)⁽²⁾
- hexane (pesticide grade)⁽²⁾
- methanol

(1) Only if sample is to be analyzed for trace metals.
(2) Only if sample is to be analyzed for organics.

1.7 PROCEDURES

As part of the health and safety plan, develop and set up a decontamination plan before any personnel or equipment enter the areas of potential exposure. The equipment decontamination plan should include:

- the number, location, and layout of decontamination stations
- which decontamination apparatus is needed
- the appropriate decontamination methods
- methods for disposal of contaminated clothing, apparatus, and solutions

1.7.1 Decontamination Methods

All personnel, samples, and equipment leaving the contaminated area of a site must be decontaminated. Various decontamination methods will either physically remove contaminants, inactivate contaminants by disinfection or sterilization, or do both.

In many cases, gross contamination can be removed by physical means. The physical decontamination techniques appropriate for equipment decontamination can be grouped into two categories: abrasive methods and non-abrasive methods.

Abrasive Cleaning Methods

Abrasive cleaning methods work by rubbing and wearing away the top layer of the surface containing the contaminant. The following abrasive methods are available:

- Mechanical: Mechanical cleaning methods use brushes of metal or nylon. The amount and type of contaminants removed will vary with the hardness of bristles, length of brushing time, and degree of brush contact.
- Air Blasting: Air blasting is used for cleaning large equipment, such as bulldozers, drilling rigs or auger bits. The equipment used in air blast cleaning employs compressed air to force abrasive material through a nozzle at high velocities. The distance between the nozzle and the surface cleaned, as well as the pressure of air, the time of application, and the angle at which the abrasive strikes the surface, determines cleaning efficiency. Air blasting has several disadvantages: it is unable to control the amount of material removed, it can aerate contaminants, and it generates large amounts of waste.
- Wet Blasting: Wet blast cleaning, also used to clean large equipment, involves use of a suspended fine abrasive delivered by compressed air to the contaminated area. The amount of materials removed can be carefully controlled by using very fine abrasives. This method generates a large amount of waste.

Non-Abrasive Cleaning Methods

Non-abrasive cleaning methods work by forcing the contaminant off of a surface with pressure. In general, less of the equipment surface is removed using non-abrasive methods. The following non-abrasive methods are available:

- High-Pressure Water: This method consists of a high-pressure pump, an operator-controlled directional nozzle, and a high pressure hose. Operating pressure usually ranges from 340 to 680 atmospheres (atm) which relates to flow rates of 20 to 140 liters per minute.
- Ultra-High-Pressure Water: This system produces a pressurized water jet (from 1,000 to 4,000 atm). The ultra-high-pressure spray removes tightly-adhered surface film. The water velocity ranges from 500 m/sec (1,000 atm) to 900 m/sec (4,000 atm). Additives can enhance the method. This method is not applicable for hand-held sampling equipment.

Disinfection/Rinse Methods

- Disinfection: Disinfectants are a practical means of inactivating infectious agents.
- Sterilization: Standard sterilization methods involve heating the equipment. Sterilization is impractical for large equipment.
- Rinsing: Rinsing removes contaminants through dilution, physical attraction, and solubilization.

1.7.2 Field Sampling Equipment Cleaning Procedures

Solvent rinses are not necessarily required when organics are not a contaminant of concern and may be eliminated from the sequence specified below. Similarly, an acid rinse is not required if analysis does not include inorganics.

- 1. Where applicable, follow physical removal procedures specified in section 1.7.1.
- 2. Wash equipment with a non-phosphate detergent solution.
- 3. Rinse with tap water.
- 4. Rinse with distilled/deionized water.
- Rinse with 10% nitric acid if the sample will be analyzed for trace organics.

- 6. Rinse with distilled/deionized water.
- 7. Use a solvent rinse (pesticide grade) if the sample will be analyzed for organics.
- 8. Air dry the equipment completely.
- 9. Rinse again with distilled/deionized water.

Selection of the solvent for use in the decontamination process is based on the contaminants present at the site. Use of a solvent is required when organic contamination is present on-site. Typical solvents used for removal of organic contaminants include acetone, hexane, or water. An acid rinse step is required if metals are present on-site. If a particular contaminant fraction is not present at the site, the nine-step decontamination procedure listed above may be modified for site specificity. The decontamination solvent used should not be among the contaminants of concern at the site.

Table 1 lists solvent rinses which may be required for elimination of particular chemicals. After each solvent rinse, the equipment should be air dried and rinsed with distilled/deionized water.

Sampling equipment that requires the use of plastic tubing should be disassembled and the tubing replaced with clean tubing, before commencement of sampling and between sampling locations.

1.8 CALCULATIONS

This section is not applicable to this SOP.

1.9 QUALITY ASSURANCE/ QUALITY CONTROL

One type of quality control sample specific to the field decontamination process is the rinsate blank. The rinsate blank provides information on the effectiveness of the decontamination process employed in the field. When used in conjunction with field blanks and trip blanks, a rinsate blank can detect contamination during sample handling, storage and sample transportation to the laboratory.

Table 1: Recommended Solvent Rinse for Soluble Contaminants

SOLVENT	SOLUBLE CONTAMINANTS		
Water	 Low-chain hydrocarbons Inorganic compounds Salts Some organic acids and other polar compounds 		
Dilute Acids	 Basic (caustic) compounds Amines Hydrazines 		
Dilute Bases for example, detergent and soap	 Metals Acidic compounds Phenol Thiols Some nitro and sulfonic compounds 		
Organic Solvents ⁽¹⁾ - for example, alcohols, ethers, ketones, aromatics, straight-chain alkanes (e.g., hexane), and common petroleum products (e.g., fuel, oil, kerosene)	Nonpolar compounds (e.g., some organic compounds)		

^{(1) -} WARNING: Some organic solvents can permeate and/or degrade protective clothing.

A rinsate blank consists of a sample of analyte-free (i.e, deionized) water which is passed over and through a field decontaminated sampling device and placed in a clean sample container.

Rinsate blanks should be run for all parameters of interest at a rate of 1 per 20 for each parameter, even if samples are not shipped that day. Rinsate blanks are not required if dedicated sampling equipment is used.

1.10 DATA VALIDATION

This section is not applicable to this SOP.

1.11 HEALTH AND SAFETY

When working with potentially hazardous materials, follow U.S. EPA, OSHA and specific health and safety procedures.

Decontamination can pose hazards under certain circumstances even though performed to protect

health and safety. Hazardous substances may be incompatible with decontamination methods. For example, the decontamination solution or solvent may react with contaminants to produce heat, explosion, or toxic products. Decontamination methods may be incompatible with clothing or equipment; some solvents can permeate or degrade protective clothing. Also, decontamination solutions and solvents may pose a direct health hazard to workers through inhalation or skin contact, or if they combust.

The decontamination solutions and solvents must be determined to be compatible before use. Any method that permeates, degrades, or damages personal protective equipment should not be used. If decontamination methods pose a direct health hazard, measures should be taken to protect personnel or the methods should be modified to eliminate the hazard.

2.0 SOIL SAMPLING: SOP #2012

2.1 SCOPE AND APPLICATION

The purpose of this Standard Operating Procedure (SOP) is to describe the procedures for collecting representative soil samples. Analysis of soil samples may determine whether concentrations of specific soil pollutants exceed established action levels, or if the concentrations of soil pollutants present a risk to public health, welfare, or the environment.

2.2 METHOD SUMMARY

Soil samples may be collected using a variety of methods and equipment. The methods and equipment used are dependent on the depth of the desired sample, the type of sample required (disturbed versus undisturbed), and the type of soil. Near-surface soils may be easily sampled using a spade, trowel, and scoop. Sampling at greater depths may be performed using a hand auger, a trier, a split-spoon, or, if required, a backhoe.

2.3 SAMPLE PRESERVATION, CONTAINERS, HANDLING, AND STORAGE

Chemical preservation of solids is not generally recommended. Refrigeration to 4°C, supplemented by a minimal holding time, is usually the best approach.

2.4 INTERFERENCES AND POTENTIAL PROBLEMS

There are two primary interferences or potential problems associated with soil sampling. These include cross-contamination of samples and improper sample collection. Cross-contamination problems can be eliminated or minimized through the use of dedicated sampling equipment. If this is not possible or practical, then decontamination of sampling equipment is necessary. Improper sample collection can involve using contaminated equipment, disturbance of the matrix resulting in compaction of the sample, or inadequate homogenization of the samples where required,

resulting in variable, non-representative results.

2.5 EQUIPMENT/APPARATUS

- sampling plan
- maps/plot plan
- safety equipment, as specified in the health and safety plan
- compass
- tape measure
- survey stakes or flags
- · camera and film
- stainless steel, plastic, or other appropriate homogenization bucket or bowl
- 1-quart mason jars w/Teflon liners
- Ziploc plastic bags
- logbook
- labels
- chain of custody forms and seals
- field data sheets
- cooler(s)
- ice
- decontamination supplies/equipment
- canvas or plastic sheet
- spade or shovel
- spatula
- scoop
- plastic or stainless steel spoons
- trowel
- continuous flight (screw) auger
- bucket auger
- post hole auger
- extension rods
- T-handle
- sampling trier
- thin-wall tube sampler
- Vehimeyer soil sampler outfit
 - tubes
 - points
 - drive head
 - drop hammer
 - puller jack and grip
- backhoe

2.6 REAGENTS

Reagents are not used for the preservation of soil samples. Decontamination solutions are specified in

ERT SOP #2006, Sampling Equipment Decontamination.

2.7 PROCEDURES

2.7.1 Preparation

- 1. Determine the extent of the sampling effort, the sampling methods to be employed, and which equipment and supplies are required.
- 2. Obtain necessary sampling and monitoring equipment.
- 3. Decontaminate or preclean equipment, and ensure that it is in working order.
- 4. Prepare schedules, and coordinate with staff, client, and regulatory agencies, if appropriate.
- 5. Perform a general site survey prior to site entry in accordance with the site-specific health and safety plan.
- 6. Use stakes, buoys, or flagging to identify and mark all sampling locations. Consider specific site factors, including extent and nature of contaminant, when selecting sample location. If required, the proposed locations may be adjusted based on site access, property boundaries, and surface obstructions. All staked locations will be utility-cleared by the property owner prior to soil sampling.

2.7.2 Sample Collection

Surface Soil Samples

Collect samples from near-surface soil with tools such as spades, shovels, and scoops. Surface material can be removed to the required depth with this equipment, then a stainless steel or plastic scoop can be used to collect the sample.

This method can be used in most soil types but is limited to sampling near surface areas. Accurate, representative samples can be collected with this procedure depending on the care and precision demonstrated by the sampling team member. The use of a flat, pointed mason trowel to cut a block of the desired soil can be helpful when undisturbed profiles are required. A stainless steel scoop, lab spoon, or plastic spoon will suffice in most other

applications. Avoid the use of devices plated with chrome or other materials. Plating is particularly common with garden implements such as potting trowels.

Follow these procedures to collect surface soil samples.

- 1. Carefully remove the top layer of soil or debris to the desired sample depth with a pre-cleaned spade.
- 2. Using a pre-cleaned, stainless steel scoop, plastic spoon, or trowel, remove and discard a thin layer of soil from the area which came in contact with the spade.
- 3. If volatile organic analysis is to be performed, transfer a portion of the sample directly into an appropriate, labeled sample container(s) with a stainless steel lab spoon, plastic lab spoon, or equivalent and secure the cap(s) tightly. Place the remainder of the sample into a stainless other plastic, or appropriate homogenization container, and mix thoroughly to obtain a homogenous sample representative of the entire sampling interval. Then, either place the sample into an appropriate, labeled container(s) and secure the cap(s) tightly; or, if composite samples are to be collected, place a sample from another sampling interval into the homogenization container and mix thoroughly. When compositing is complete, place the sample into appropriate, labeled container(s) and secure the cap(s) tightly.

Sampling at Depth with Augers and Thin-Wall Tube Samplers

This system consists of an auger, a series of extensions, a "T" handle, and a thin-wall tube sampler (Appendix A, Figure 1). The auger is used to bore a hole to a desired sampling depth, and is then withdrawn. The sample may be collected directly from the auger. If a core sample is to be collected, the auger tip is then replaced with a thin-wall tube sampler. The system is then lowered down the borehole, and driven into the soil at the completion depth. The system is withdrawn and the core collected from the thin-wall tube sampler.

Several types of augers are available. These include: bucket, continuous flight (screw), and posthole augers. Bucket augers are better for direct

sample recovery since they provide a large volume of sample in a short time. When continuous flight augers are used, the sample can be collected directly from the flights, which are usually at 5-feet intervals. The continuous flight augers are satisfactory for use when a composite of the complete soil column is desired. Posthole augers have limited utility for sample collection as they are designed to cut through fibrous, rooted, swampy soil.

Follow these procedures for collecting soil samples with the auger and a thin-wall tube sampler.

- 1. Attach the auger bit to a drill rod extension, and attach the "T" handle to the drill rod.
- Clear the area to be sampled of any surface debris (e.g., twigs, rocks, litter). It may be advisable to remove the first 3 to 6 inches of surface soil for an area approximately 6 inches in radius around the drilling location.
- 3. Begin augering, periodically removing and depositing accumulated soils onto a plastic sheet spread near the hole. This prevents accidental brushing of loose material back down the borehole when removing the auger or adding drill rods. It also facilitates refilling the hole, and avoids possible contamination of the surrounding area.
- 4. After reaching the desired depth, slowly and carefully remove the auger from boring. When sampling directly from the auger, collect sample after the auger is removed from boring and proceed to Step 10.
- 5. Remove auger tip from drill rods and replace with a pre-cleaned thin-wall tube sampler. Install proper cutting tip.
- 6. Carefully lower the tube sampler down the borehole. Gradually force the tube sampler into the soil. Care should be taken to avoid scraping the borehole sides. Avoid hammering the drill rods to facilitate coring as the vibrations may cause the boring walls to collapse.
- Remove the tube sampler, and unscrew the drill rods.
- 8. Remove the cutting tip and the core from the device.

- Discard the top of the core (approximately 1 inch), as this represents material collected before penetration of the layer of concern. Place the remaining core into the appropriate labeled sample container(s). Sample homogenization is not required.
- 10. If volatile organic analysis is to be performed, transfer a portion of the sample directly into an appropriate, labeled sample container(s) with a stainless steel lab spoon, plastic lab spoon, or equivalent and secure the cap(s) tightly. Place the remainder of the sample into a stainless other steel. plastic, or appropriate homogenization container, and mix thoroughly to obtain a homogenous sample representative of the entire sampling interval. Then, either place the sample into an appropriate, labeled container(s) and secure the cap(s) tightly; or, if composite samples are to be collected, place a sample from another sampling interval into the homogenization container and mix thoroughly. When compositing is complete, place the into the appropriate. labeled container(s) and secure the cap(s) tightly.
- 11. If another sample is to be collected in the same hole, but at a greater depth, reattach the auger bit to the drill and assembly, and follow steps 3 through 11, making sure to decontaminate the auger and tube sampler between samples.
- 12. Abandon the hole according to applicable state regulations. Generally, shallow holes can simply be backfilled with the removed soil material.

Sampling at Depth with a Trier

The system consists of a trier, and a "T" handle. The auger is driven into the soil to be sampled and used to extract a core sample from the appropriate depth.

Follow these procedures to collect soil samples with a sampling trier.

- 1. Insert the trier (Appendix A, Figure 2) into the material to be sampled at a 0° to 45° angle from horizontal. This orientation minimizes the spillage of sample.
- 2. Rotate the trier once or twice to cut a core of material.

- 3. Slowly withdraw the trier, making sure that the slot is facing upward.
- 4. If volatile organic analysis is to be performed, transfer a portion of the sample directly into an appropriate, labeled sample container(s) with a stainless steel lab spoon, plastic lab spoon, or equivalent and secure the cap(s) tightly. Place the remainder of the sample into a stainless steel, plastic, or other appropriate homogenization container, and mix thoroughly to obtain a homogenous sample representative of the entire sampling interval. Then, either place the sample into an appropriate, labeled container(s) and secure the cap(s) tightly; or, if composite samples are to be collected, place a sample from another sampling interval into the homogenization container and mix thoroughly. When compositing is complete, place the sample into an appropriate, labeled container(s) and secure the cap(s) tightly.

Sampling at Depth with a Split Spoon (Barrel) Sampler

The procedure for split spoon sampling describes the collection and extraction of undisturbed soil cores of 18 or 24 inches in length. A series of consecutive cores may be extracted with a split spoon sampler to give a complete soil column profile, or an auger may be used to drill down to the desired depth for sampling. The split spoon is then driven to its sampling depth through the bottom of the augured hole and the core extracted.

When split tube sampling is performed to gain geologic information, all work should be performed in accordance with ASTM D 1586-67 (reapproved 1974).

Follow these procedures for collecting soil samples with a split spoon.

- 1. Assemble the sampler by aligning both sides of the barrel and then screwing the bit onto the bottom and the heavier head piece onto the top.
- 2. Place the sampler in a perpendicular position on the sample material.
- 3. Using a sledge hammer or well ring, if available, drive the tube. Do not drive past the bottom of the head piece or compression of the

sample will result.

- 4. Record in the site logbook or on field data sheets the length of the tube used to penetrate the material being sampled, and the number of blows required to obtain this depth.
- 5. Withdraw the sampler, and open by unscrewing the bit and head and splitting the barrel. If a split sample is desired, a cleaned, stainless steel knife should be used to divide the tube contents in half, longitudinally. This sampler is typically available in diameters of 2 and 3 1/2 inches. However, in order to obtain the required sample volume, use of a larger barrel may be required.
- 6. Without disturbing the core, transfer it to an appropriate labeled sample container(s) and seal tightly.

Test Pit/Trench Excavation

These relatively large excavations are used to remove sections of soil, when detailed examination of soil characteristics (horizontal structure, color, etc.) are required. It is the least cost effective sampling method due to the relatively high cost of backhoe operation.

Follow these procedures for collecting soil samples from test pit/trench excavations.

- Prior to any excavation with a backhoe, it is important to ensure that all sampling locations are clear of utility lines and poles (subsurface as well as above surface).
- 2. Using the backhoe, dig a trench to approximately 3 feet in width and approximately 1 foot below the cleared sampling location. Place removed or excavated soils on plastic sheets. Trenches greater than 5 feet deep must be sloped or protected by a shoring system, as required by OSHA regulations.
- Use a shovel to remove a 1- to 2-inch layer of soil from the vertical face of the pit where sampling is to be done.
- 4. Take samples using a trowel, scoop, or coring device at the desired intervals. Be sure to scrape the vertical face at the point of sampling

to remove any soil that may have fallen from above, and to expose fresh soil for sampling. In many instances, samples can be collected directly from the backhoe bucket.

- 5. If volatile organic analysis is to be performed, transfer a portion of the sample directly into an appropriate, labeled sample container(s) with a stainless steel lab spoon, plastic lab spoon, or equivalent and secure the cap(s) tightly. Place the remainder of the sample into a stainless plastic, or other appropriate homogenization container, and mix thoroughly to obtain a homogenous sample representative of the entire sampling interval. Then, either place the sample into an appropriate, labeled container(s) and secure the cap(s) tightly; or, if composite samples are to be collected, place a sample from another sampling interval into the homogenization container and mix thoroughly. When compositing is complete, place the sample into appropriate, labeled container(s) and secure the cap(s) tightly.
- Abandon the pit or excavation according to applicable state regulations. Generally, shallow excavations can simply be backfilled with the removed soil material.

2.8 CALCULATIONS

This section is not applicable to this SOP.

2.9 QUALITY ASSURANCE/ QUALITY CONTROL

There are no specific quality assurance activities which apply to the implementation of these procedures. However, the following QA procedures apply:

- All data must be documented on field data sheets or within site logbooks.
- All instrumentation must be operated in accordance with operating instructions as supplied by the manufacturer, unless otherwise specified in the work plan. Equipment checkout and calibration activities must occur prior to sampling/operation, and they must be documented.

2.10 DATA VALIDATION

This section is not applicable to this SOP.

2.11 HEALTH AND SAFETY

When working with potentially hazardous materials, follow U.S. EPA, OSHA, and specific health and safety procedures.

3.1 SCOPE AND APPLICATION

Soil gas monitoring provides a quick means of waste site evaluation. Using this method, underground contamination can be identified, and the source, extent, and movement of the pollutants can be traced.

This Standard Operating Procedure (SOP) outlines the methods used by EPA/ERT in installing soil gas wells; measuring organic levels in the soil gas using an HNU PI 101 Portable Photoionization Analyzer and/or other air monitoring devices; and sampling the soil gas using Tedlar bags, Tenax sorbent tubes, and SUMMA canisters.

3.2 METHOD SUMMARY

A 3/8-inch diameter hole is driven into the ground to a depth of 4 to 5 feet using a commercially available "slam bar". (Soil gas can also be sampled at other depths by the use of a longer bar or bar attachments.) A 1/4-inch O.D. stainless steel probe is inserted into the hole. The hole is then sealed at the top around the probe using modeling clay. The gas contained in the interstitial spaces of the soil is sampled by pulling the sample through the probe using an air sampling pump. The sample may be stored in Tedlar bags, drawn through sorbent cartridges, or analyzed directly using a direct reading instrument.

The air sampling pump is not used for SUMMA canister sampling of soil gas. Sampling is achieved by soil gas equilibration with the evacuated SUMMA canister. Other field air monitoring devices, such as the combustible gas indicator (MSA CGI/02 Meter, Model 260) and the organic vapor analyzer (Foxboro OVA, Model 128), can also be used depending on specific site conditions. Measurement of soil temperature using a temperature probe may also be desirable. Bagged samples are usually analyzed in a field laboratory using a portable Photovac GC.

Power driven sampling probes may be utilized when soil conditions make sampling by hand unfeasible (i.e., frozen ground, very dense clays, pavement, etc.). Commercially available soil gas sampling probes (hollow, 1/2-inch O.D. steel probes) can be driven to the desired depth using a power hammer (e.g., Bosch Demolition Hammer). Samples can be drawn through the probe itself, or through Teflon tubing inserted through the probe and attached to the probe point. Samples are collected and analyzed as described above.

3.3 SAMPLE PRESERVATION, CONTAINERS, HANDLING, AND STORAGE

3.3.1 Tedlar Bag

Soil gas samples are generally contained in 1-L Tedlar bags. Bagged samples are best stored in coolers to protect the bags from any damage that may occur in the field or in transit. In addition, coolers ensure the integrity of the samples by keeping them at a cool temperature and out of direct sunlight. Samples should be analyzed as soon as possible, preferably within 24 to 48 hours.

3.3.2 Tenax Tube

Bagged samples can also be drawn into Tenax or other sorbent tubes to undergo lab GC/MS analysis. If Tenax tubes are to be utilized, special care must be taken to avoid contamination. Handling of the tubes should be kept to a minimum, and samplers must wear nylon or other lint-free gloves. After sampling, each tube should be stored in a clean, sealed culture tube; the ends packed with clean glass wool to protect the sorbent tube from breakage. The culture tubes should be kept cool and wrapped in aluminum foil to prevent any photodegradation of samples (see Section 3.7.4.).

3.3.3 SUMMA Canister

The SUMMA canisters used for soil gas sampling have a 6-L sample capacity and are certified clean by GC/MS analysis before being utilized in the field. After sampling is completed, they are stored and shipped in travel cases.

3.4 INTERFERENCES AND POTENTIAL PROBLEMS

3.4.1 HNU Measurements

A number of factors can affect the response of the HNU PI 101. High humidity can cause lamp fogging and decreased sensitivity. This can be significant when soil moisture levels are high, or when a soil gas well is actually in groundwater. High concentrations of methane can cause a downscale deflection of the meter. High and low temperature, electrical fields, FM radio transmission, and naturally occurring compounds, such as terpenes in wooded areas, will also affect instrument response.

Other field screening instruments can be affected by interferences. Consult the manufacturers' manuals.

3.4.2 Factors Affecting Organic Concentrations in Soil Gas

Concentrations in soil gas are affected by dissolution, adsorption, and partitioning. Partitioning refers to the ratio of component found in a saturated vapor above an aqueous solution to the amount in the solution; this can, in theory, be calculated using the Henry's Law constants. Contaminants can also be adsorbed onto inorganic soil components or "dissolved" in organic components. These factors can result in a lowering of the partitioning coefficient.

Soil "tightness" or amount of void space in the soil matrix, will affect the rate of recharging of gas into the soil gas well.

Existence of a high, or perched, water table, or of an impermeable underlying layer (such as a clay lens or layer of buried slag) may interfere with sampling of the soil gas. Knowledge of site geology is useful in such situations, and can prevent inaccurate sampling.

3.4.3 Soil Probe Clogging

A common problem with this sampling method is soil probe clogging. A clogged probe can be identified by using an in-line vacuum gauge or by listening for the sound of the pump laboring. This problem can usually be eliminated by using a wire cable to clear the probe (see procedure #3 in Section 3.7.1).

3.4.4 Underground Utilities

Prior to selecting sample locations, an underground utility search is recommended. The local utility companies can be contacted and requested to mark the locations of their underground lines. Sampling plans can then be drawn up accordingly. Each sample location should also be screened with a metal detector or magnetometer to verify that no underground pipes or drums exist.

3.5 EQUIPMENT/APPARATUS

3.5.1 Slam Bar Method

- slam bar (one per sampling team)
- soil gas probes, stainless steel tubing, 1/4-inch O.D., 5 foot length
- flexible wire or cable used for clearing the tubing during insertion into the well
- "quick connect" fittings to connect sampling probe tubing, monitoring instruments, and Gilian pumps to appropriate fittings on vacuum box
- modeling clay
- vacuum box for drawing a vacuum around Tedlar bag for sample collection (one per sampling team)
- Gilian pump Model HFS113A adjusted to approximately 3.0 L/min (one to two per sampling team)
- 1/4-inch Teflon tubing, 2 to 3 foot lengths, for replacement of contaminated sample line
- Tedlar bags, 1 liter, at least one bag per sample point
- soil gas sampling labels, field data sheets, logbook, etc.
- HNU Model PI 101, or other field air monitoring devices, (one per sampling team)
- ice chest, for carrying equipment and for protection of samples (two per sampling team)
- metal detector or magnetometer, for detecting underground utilities/ pipes/drums (one per sampling team)
- Photovac GC, for field-lab analysis of bagged samples
- SUMMA canisters (plus their shipping cases) for sample, storage and transportation

3.5.2 Power Hammer Method

- Bosch demolition hammer
- 1/2-inch O.D. steel probes, extensions, and points
- dedicated aluminum sampling points
- Teflon tubing, 1/4-inch O.D.
- "quick connect" fittings to connect sampling probe tubing, monitoring instruments, and Gilian pumps to appropriate fittings on vacuum box
- modeling clay
- vacuum box for drawing a vacuum around Tedlar bag for sample collection (one per sampling team)
- Gilian pump Model HFS113A adjusted to approximately 3.0 L/min (one to two per sampling team)
- 1/4-inch Teflon tubing, 2 to 3 foot lengths, for replacement of contaminated sample line
- Tedlar bags, 1 liter, at least one bag per sample point
- soil gas sampling labels, field data sheets, logbook, etc.
- HNU Model PI 101, or other field air monitoring devices, (one per sampling team)
- ice chest, for carrying equipment and for protection of samples (two per sampling team)
- metal detector or magnetometer, for detecting underground utilities/ pipes/drums (one per sampling team)
- Photovac GC, for field-lab analysis of bagged samples
- SUMMA canisters (plus their shipping cases) for sample, storage and transportation
- generator with extension cords
- high lift jack assembly for removing probes

3.6 REAGENTS

- HNU Systems Inc. Calibration Gas for HNU Model PI 101, and/or calibration gas for other field air monitoring devices
- deionized organic-free water, for decontamination
- methanol, HPLC grade, for decontamination
- ultra-zero grade compressed air, for field blanks

standard gas preparations for Photovac GC calibration and Tedlar bag spikes

3.7 PROCEDURES

3.7.1 Soil Gas Well Installation

- 1. Initially, make a hole slightly deeper than the desired depth. For sampling up to 5 feet, use a 5-foot single piston slam bar. For deeper depths, use a piston slam bar with threaded 4-foot-long extensions. Other techniques can be used, so long as holes are of narrow diameter and no contamination is introduced.
- 2. After the hole is made, carefully withdraw the slam bar to prevent collapse of the walls of the hole. Then insert the soil gas probe.
- 3. It is necessary to prevent plugging of the probe, especially for deeper holes. Place a metal wire or cable, slightly longer than the probe, into the probe prior to inserting into the hole. Insert the probe to full depth, then pull it up 3 to 6 inches, then clear it by moving the cable up and down. The cable is removed before sampling.
- 4. Seal the top of the sample hole at the surface against ambient air infiltration by using modeling clay molded around the probe at the surface of the hole.
- 5. If conditions preclude hand installation of the soil gas wells, the power driven system may be employed. Use the generator-powered demolition hammer to drive the probe to the desired depth (up to 12 feet may be attained with extensions). Pull the probe up 1 to 3 inches if the retractable point is used. No clay is needed to seal the hole. After sampling, retrieve the probe using the high lift jack assembly.
- 6. If semi-permanent soil gas wells are required, use the dedicated aluminum probe points. Insert these points into the bottom of the power-driven probe and attach it to the Teflon tubing. Insert the probe as in step 5. When the probe is removed, the point and Teflon tube remain in the hole, which may be sealed by backfilling with sand, bentonite, or soil.

3.7.2 Screening with Field Instruments

- 1. The well volume must be evacuated prior to sampling. Connect the Gilian pump, adjusted to 3.0 L/min, to the sample probe using a section of Teflon tubing as a connector. Turn the pump on, and a vacuum is pulled through the probe for approximately 15 seconds. A longer time is required for sample wells of greater depths.
- 2. After evacuation, connect the monitoring instrument(s) to the probe using a Teflon connector. When the reading is stable, or peaks, record the reading. For detailed procedures on HNU field protocol, see appendix B, and refer to the manufacturer's instructions.
- 3. Some readings may be above or below the range set on the field instruments. The range may be reset, or the response recorded as a figure greater than or less than the range. Consider the recharge rate of the well with soil gas when sampling at a different range setting.

3.7.3 Tedlar Bag Sampling

- 1. Follow step 1 in section 3.7.2 to evacuate well volume. If air monitoring instrument screening was performed prior to sampling, evacuation is not necessary.
- 2. Use the vacuum box and sampling train (Figure 3 in Appendix A) to take the sample. The sampling train is designed to minimize the introduction of contaminants and losses due to adsorption. All wetted parts are either Teflon or stainless steel. The vacuum is drawn indirectly to avoid contamination from sample pumps.
- 3. Place the Tedlar bag inside the vacuum box, and attach it to the sampling port. Attach the sample probe to the sampling port via Teflon tubing and a "quick connect" fitting.
- 4. Draw a vacuum around the outside of the bag, using a Gilian pump connected to the vacuum box evacuation port, via Tygon tubing and a "quick connect" fitting. The vacuum causes the bag to inflate, drawing the sample.

5. Break the vacuum by removing the Tygon line from the pump. Remove the bagged sample from the box and close valve. Label bag, record data on data sheets or in logbooks. Record the date, time, sample location ID, and the HNU, or other instrument reading(s) on sample bag label.

CAUTION: Labels should not be pasted directly onto the bags, nor should bags be labeled directly using a marker or pen. Inks and adhesive may diffuse through the bag material, contaminating the sample. Place labels on the edge of the bags, or tie the labels to the metal eyelets provided on the bags. Markers with inks containing volatile organics (i.e., permanent ink markers) should not be used.

3.7.4 Tenax Tube Sampling

Samples collected in Tedlar bags may be sorbed onto Tenax tubes for further analysis by GC/MS.

Additional Apparatus

- Syringe with a luer-lock tip capable of drawing a soil gas or air sample from a Tedlar bag onto a Tenax/CMS sorbent tube. The syringe capacity is dependent upon the volume of sample being drawn onto the sorbent tube.
- Adapters for fitting the sorbent tube between the Tedlar bag and the sampling syringe. The adapter attaching the Tedlar bag to the sorbent tube consists of a reducing union (1/4-inch to 1/16-inch O.D. -- Swagelok cat. # SS-400-6-ILV or equivalent) with a length of 1/4-inch O.D. Teflon tubing replacing the nut on the 1/6-inch (Tedlar bag) side. A 1/4-inch I.D. silicone O-ring replaces the ferrules in the nut on the 1/4-inch (sorbent tube) side of the union.

The adapter attaching the sampling syringe to the sorbent tube consists of a reducing union (1/4-inch to 1/16-inch O.D. --Swagelok Cat. # SS-400-6-ILV or equivalent) with a 1/4-inch I.D. silicone O-ring replacing the ferrules in the nut on the 1/4-inch (sorbent tube) side and the needle of a luer-lock syringe needle inserted into the 1/16-inch side (held in place with a 1/16-inch ferrule). The

luer-lock end of the needle can be attached to the sampling syringe. It is useful to have a luer-lock on/off valve situated between the syringe and the needle.

• Two-stage glass sampling cartridge (1/4-inch O.D. x 1/8-inch I.D. x 5 1/8 inch) contained in a flame-sealed tube (manufactured by Supelco Custom Tenax/Spherocarb Tubes or equivalent) containing two sorbent sections retained by glass wool:

Front section: 150 mg of Tenax-GC Back section: 150 mg of CMS (Carbonized Molecular Sieve)

Sorbent tubes may also be prepared in the lab and stored in either Teflon-capped culture tubes or stainless steel tube containers. Sorbent tubes stored in this manner should not be kept more than 2 weeks without reconditioning. (See SOP #2052 for Tenax/CMS sorbent tube preparation).

- Teflon-capped culture tubes or stainless steel tube containers for sorbent tube storage. These containers should be conditioned by baking at 120°C for at least 2 hours. The culture tubes should contain a glass wool plug to prevent sorbent tube breakage during transport. Reconditioning of the containers should occur between usage or after extended periods of disuse (i.e., 2 weeks or more).
- Nylon gloves or lint-free cloth. (Hewlett Packard Part # 8650-0030 or equivalent.)

Sample Collection

- Handle sorbent tubes with care, using nylon gloves (or other lint-free material) to avoid contamination.
- 2. Immediately before sampling, break one end of the sealed tube and remove the Tenax cartridge. For in-house prepared tubes, remove cartridge from its container.
- 3. Connect the valve on the Tedlar bag to the sorbent tube adapter. Connect the sorbent tube to the sorbent tube adapter with the Tenax

(white granular) side of the tube facing the Tedlar bag.

- 4. Connect the sampling syringe assembly to the CMS (black) side of the sorbent tube. Fittings on the adapters should be very tight.
- 5. Open the valve on the Tedlar bag.
- 6. Open the on/off valve of the sampling syringe.
- 7. Draw a predetermined volume of sample onto the sorbent tube. (This may require closing the syringe valve, emptying the syringe and then repeating the procedure, depending upon the syringe capacity and volume of sample required.)
- 8. After sampling, remove the tube from the sampling train with gloves or a clean cloth. Do not label or write on the Tenax/CMS tube.
- Place the sorbent tube in a conditioned stainless steel tube holder or culture tube. Culture tube caps should be sealed with Teflon tape.

Sample Labeling

Each sample tube container (not tube) must be labeled with the site name, sample station number, sample date, and sample volume.

Chain of custody forms must accompany all samples to the laboratory.

Quality Assurance

Before field use, a QA check should be performed on each batch of sorbent tubes by analyzing a tube with thermal desorption/cryogenic trapping GC/MS.

At least one blank sample must be submitted with each set of samples collected at a site. This trip blank must be treated the same as the sample tubes except no sample will be drawn through the tube.

Sample tubes should be stored out of UV light (i.e., sunlight) and kept on ice until analysis.

Samples should be taken in duplicate, when possible.

3.7.5 SUMMA Canister Sampling

- Follow item 1 in step 3.7.2 to evacuate well volume. If HNU analysis was performed prior to taking a sample, evacuation is not necessary.
- 2. Attach a certified clean, evacuated 6-L SUMMA canister via the 1/4-inch Teflon tubing.
- 3. Open the valve on SUMMA canister. The soil gas sample is drawn into the canister by pressure equilibration. The approximate sampling time for a 6-L canister is 20 minutes.
- 4. Site name, sample location, number, and date must be recorded on a chain of custody form and on a blank tag attached to the canister.

3.8 CALCULATIONS

3.8.1 Field Screening Instruments

Instrument readings are usually read directly from the meter. In some cases, the background level at the soil gas station may be subtracted:

Final Reading = Sample Reading - Background

3.8.2 Photovac GC Analysis

Calculations used to determine concentrations of individual components by Photovac GC analysis are beyond the scope of this SOP and are covered in ERT SOP #2109, Photovac GC Analysis for Soil, Water and Air/Soil Gas.

3.9 QUALITY ASSURANCE/ QUALITY CONTROL

3.9.1 Field Instrument Calibration

Consult the manufacturers' manuals for correct use and calibration of all instrumentation. The HNU should be calibrated at least once a day.

3.9.2 Gilian Model HFS113A Air Sampling Pump Calibration

Flow should be set at approximately 3.0 L/min;

accurate flow adjustment is not necessary. Pumps should be calibrated prior to bringing into the field.

3.9.3 Sample Probe Contamination

Sample probe contamination is checked between each sample by drawing ambient air through the probe via a Gilian pump and checking the response of the HNU PI 101. If HNU readings are higher than background, replacement or decontamination is necessary.

Sample probes may be decontaminated simply by drawing ambient air through the probe until the HNU reading is at background. More persistent contamination can be washed out using methanol and water, then air drying. Having more than one probe per sample team will reduce lag times between sample stations while probes are decontaminated.

3.9.4 Sample Train Contamination

The Teflon line forming the sample train from the probe to the Tedlar bag should be changed on a daily basis. If visible contamination (soil or water) is drawn into the sampling train, it should be changed immediately. When sampling in highly contaminated areas, the sampling train should be purged with ambient air, via a Gilian pump, for approximately 30 seconds between each sample. After purging, the sampling train can be checked using an HNU, or other field monitoring device, to establish the cleanliness of the Teflon line.

3.9.5 Field Blank

Each cooler containing samples should also contain one Tedlar bag of ultra-zero grade air, acting as a field blank. The field blank should accompany the samples in the field (while being collected) and when they are delivered for analysis. A fresh blank must be provided to be placed in the empty cooler pending additional sample collection. One new field blank per cooler of samples is required. A chain of custody form must accompany each cooler of samples and should include the blank that is dedicated to that group of samples.

3.9.6 Trip Standard

Each cooler containing samples should contain a Tedlar bag of standard gas to calibrate the analytical instruments (Photovac GC, etc.). This trip standard will be used to determine any changes in concentrations of the target compounds during the course of the sampling day (e.g., migration through the sample bag, degradation, or adsorption). A fresh trip standard must be provided and placed in each cooler pending additional sample collection. A chain of custody form should accompany each cooler of samples and should include the trip standard that is dedicated to that group of samples.

3.9.7 Tedlar Bag Check

Prior to use, one bag should be removed from each lot (case of 100) of Tedlar bags to be used for sampling and checked for possible contamination as follows: the test bag should be filled with ultra-zero grade air; a sample should be drawn from the bag and analyzed via Photovac GC or whatever method is to be used for sample analysis. This procedure will ensure sample container cleanliness prior to the start of the sampling effort.

3.9.8 SUMMA Canister Check

From each lot of four cleaned SUMMA canisters, one is to be removed for a GC/MS certification check. If the canister passes certification, then it is re-evacuated and all four canisters from that lot are available for sampling.

If the chosen canister is contaminated, then the entire lot of four SUMMA canisters must be recleaned, and a single canister is re-analyzed by GC/MS for certification.

3.9.9 Options

Duplicate Samples

A minimum of 5% of all samples should be collected in duplicate (i.e., if a total of 100 samples are to be collected, five samples should be duplicated). In choosing which samples to duplicate, the following criterion applies: if, after filling the first Tedlar bag, and, evacuating the well for 15 seconds, the second HNU (or other field monitoring device being used) reading matches or is close to (within 50%) the first reading, a duplicate sample may be taken.

Spikes

A Tedlar bag spike and Tenax tube spike may be desirable in situations where high concentrations of contaminants other than the target compounds are found to exist (landfills, etc.). The additional level of QA/QC attained by this practice can be useful in determining the effects of interferences caused by these non-target compounds. SUMMA canisters containing samples are not spiked.

3.10 DATA VALIDATION

For each target compound, the level of concentration found in the sample must be greater than three times the level (for that compound) found in the field blank which accompanied that sample to be considered valid. The same criteria apply to target compounds detected in the Tedlar bag pre-sampling contamination check.

3.11 HEALTH AND SAFETY

Because the sample is being drawn from underground, and no contamination is introduced into the breathing zone, soil gas sampling usually occurs in Level D, unless the sampling location is within the hot zone of a site, which requires Level B or Level C protection. However, to ensure that the proper level of protection is utilized, constantly monitor the ambient air using the HNU PI 101 to obtain background readings during the sampling procedure. As long as the levels in ambient air do not rise above background, no upgrade of the level of protection is needed.

Also, perform an underground utility search prior to sampling (see section 3.4.4). When working with potentially hazardous materials, follow U.S. EPA, OSHA, and specific health and safety procedures.

. ! :

4.0 General Surface Geophysics: SOP #2159

4.1 SCOPE AND APPLICATION

This Standard Operating Procedure (SOP) describes the general procedures used to acquire surface geophysical data. This data is used for delineating subsurface waste, and for interpreting geologic, hydrogeologic or other data related to hazardous waste site characterization.

The media pertinent to these surface geophysical methods are soil/rock and groundwater. The sensitivity or minimum response of a given method depends on the comparison of the object or area of study to that of its background (i.e., what the media's response would be like without the object of study). Therefore, the suitability of surface geophysical methods for a given investigation must be judged on the object's ability to be measured and the extent to which the specific setting of the study interferes with the measurement.

The surface geophysical method(s) selected for application at a site are dependent on site conditions, such as depth to bedrock, depth to target, urban disturbances (fences, power lines, surface debris, etc.) and atmospheric conditions. Detectability of the target is dependent on the sensitivity of the instrument and the variation of the field measurement from the ambient noise. Ambient noise is the pervasive noise associated with an environment. Therefore, the applicability of geophysical methods at a given site is dependent on the specific setting at that site.

Five geophysical methods may be utilized in hazardous waste site characterization: magnetometry, electromagnetics, resistivity. seismology and ground penetrating radar (GPR). Magnetometers may be used to locate buried ferrous metallic objects and geologic information. Electromagnetic methods can be used to determine the presence of metals, electrical conductivity of the terrain, and geologic information. Resistivity methods are used to determine the electrical resistivity of the terrain and geologic information. Seismic methods are useful in determining geologic stratigraphy and structure. GPR may be used to locate disturbance in the soil (i.e., trenches, buried utilities and fill boundaries) and some near-surface geologic information.

These procedures may be varied or changed as required, dependent on site conditions, equipment limitations or limitations imposed by the procedure. In all instances, the procedures employed should be documented and associated with the final report.

4.2 METHOD SUMMARY

4.2.1 Magnetics

A magnetometer is an instrument which measures magnetic field strength in units of gammas (nanoteslas). Local variations, or anomalies, in the earth's magnetic field are the result of disturbances caused mostly by variations in concentrations of ferromagnetic material in the vicinity of the magnetometer's sensor. A buried ferrous object, such as a steel drum or tank, locally distorts the earth's magnetic field and results in a magnetic anomaly. The objective of conducting a magnetic survey at a hazardous waste or groundwater pollution site is to map these anomalies and delineate the area containing buried sources of the anomalies.

Analysis of magnetic data can allow an experienced geophysicist to estimate the areal extent of buried ferrous targets, such as a steel tank or drum. Often, areas of burial can be prioritized upon examination of the data, with high priority areas indicating a near certainty of buried ferrous material. In some instances, estimates of depth of burial can be made from the data. Most of these depth estimates are graphical methods of interpretation, such as slope techniques and halfwidth rules, as described by Nettleton (1976). The accuracy of these methods is dependent upon the quality of the data and the skill of the interpreting geophysicist. An accuracy of 10 to 20 percent is considered acceptable. The magnetic method may also be used to map certain geologic features, such as igneous intrusions, which may play an important role in the hydrogeology of a groundwater pollution site.

Advantages

Advantages of using the magnetic method for the initial assessment of hazardous waste sites are the

relatively low cost of conducting the survey and the relative ease of completing a survey in a short amount of time. Little, if any, site preparation is necessary. Surveying requirements are not as stringent as for other methods and may be completed with a transit or Brunton-type pocket transit and a non-metallic measuring tape. Often, a magnetic investigation is a very cost-effective method for initial assessment of a hazardous waste site where buried steel drums or tanks are a concern.

Disadvantages

"Cultural noise" is a limitation of the magnetic method in certain areas. Man-made structures that are constructed with ferrous material, such as steel, have a detrimental effect on the quality of the data. Avoid features such as steel structures, power lines, metal fences, steel reinforced concrete, pipelines and underground utilities. When these features are unavoidable, note their locations in a field notebook and on the site map.

Another limitation of the magnetic method is the inability of the interpretation methods to differentiate between various steel objects. For instance, it is not possible to determine if an anomaly is the result of a steel tank, or a group of steel drums, or old washing machines. Also, the magnetic method does not allow the interpreter to determine the contents of a buried tank or drum.

4.2.2 Electromagnetics

The electromagnetic method is a geophysical technique based on the physical principles of inducing and detecting electrical current flow within geologic strata. A receiver detects these induced currents by measuring the resulting time-varying The electromagnetic method magnetic field. measures bulk conductivity (the inverse of resistivity) of geologic materials beneath the transmitter and receiver coils. Electromagnetics should not be confused with the electrical resistivity method. The difference between the two techniques is in the method which the electrical currents are forced to flow in the earth. In the electromagnetic method, currents are induced by the application of time-varying magnetic fields, whereas in the electrical resistivity method, current is injected into the ground through surface electrodes.

Electromagnetics can be used to locate pipes, utility

lines, cables, buried steel drums, trenches, buried waste, and concentrated contaminant plumes. The method can also be used to map shallow geologic features, such as lithologic changes and fault zones.

Advantages

Electromagnetic measurements can be collected rapidly and with a minimum number of field personnel. Most electromagnetic equipment used in groundwater pollution investigations is lightweight and easily portable. The electromagnetic method is one of the more commonly used geophysical techniques applied to groundwater pollution investigations.

Disadvantages

The main limitation of the electromagnetic method is "cultural noise". Sources of "cultural noise" can include: large metal objects, buried cables, pipes, buildings, and metal fences.

The electromagnetic method has limitations in areas where the geology varies laterally. These can cause conductivity anomalies or lineations, which might be misinterpreted as contaminant plumes.

4.2.3 Electrical Resistivity

The electrical resistivity method is used to map subsurface electrical resistivity structure, which is in turn interpreted by the geophysicist to determine the geologic structure and/or physical properties of the geologic materials. Electrical resistivities of geologic materials are measured in ohm-meters, and are functions of porosity, permeability, water saturation and the concentration of dissolved solids in the pore fluids.

Resistivity methods measure the bulk resistivity of the subsurface, as do the electromagnetic methods. The difference between the two methods is in the way that electrical currents are forced to flow in the earth. In the electrical resistivity method, current is injected into the ground through surface electrodes, whereas in electromagnetic methods currents are induced by application of time-varying magnetic fields.

Advantages

The principal advantage of the electrical resistivity method is that quantitative modeling is possible using either computer software or published master curves. The resulting models can provide accurate estimates of depths, thicknesses and resistivities of subsurface layers. The layer resistivities can then be used to estimate the resistivity of the saturating fluid, which is related to the total concentration of dissolved solids in the fluid.

Disadvantages

The limitations of using the resistivity method in groundwater pollution site investigations are largely due to site characteristics, rather than in any inherent limitations of the method. Typically, polluted sites are located in industrial areas that contain an abundance of broad spectrum electrical noise. In conducting a resistivity survey, the voltages are relayed to the receiver over long wires that are grounded at each end. These wires act as antennae receiving the radiated electrical noise that in turn degrades the quality of the measured voltages.

Resistivity surveys require a fairly large area, far removed from pipelines and grounded metallic structures such as metal fences, pipelines and railroad tracks. This requirement precludes using resistivity on many polluted sites. However, the resistivity method can often be used successfully offsite to map the stratigraphy of the area surrounding the site. A general "rule of thumb" for resistivity surveying is that grounded structures be at least half of the maximum electrode spacing distance away from the axis of the survey line.

Another consideration in the resistivity method is that the fieldwork tends to be more labor intensive than some other geophysical techniques. A minimum of two to three crew members are required for the fieldwork.

4.2.4 Seismic

Surface seismic techniques used in groundwater pollution site investigations are largely restricted to seismic refraction and seismic reflection methods. The equipment used for both methods is fundamentally the same and both methods measure the travel-time of acoustic waves propagating through the subsurface. In the refraction method, the travel-time of waves refracted along an acoustic interface is measured, and in the reflection method, the travel-time of a wave which reflects or echoes off an interface is measured.

The interpretation of seismic data will vield subsurface velocity information, which is dependent upon the acoustic properties of the subsurface Various geologic materials can be categorized by their acoustic properties or velocities. Depth to geologic interfaces are calculated using the velocities obtained from a seismic investigation. The geologic information gained from a seismic investigation is then used in the hydrogeologic assessment of a groundwater pollution site and the surrounding area. The interpretation of seismic data indicates changes in lithology or stratigraphy, geologic structure, or water saturation (water table). Seismic methods are commonly used to determine depth and structure of geologic and hydrogeologic units, to estimate hydraulic conductivity, to detect cavities or voids, to determine structure stability, to detect fractures and fault zones, and to estimate ripability. The choice of method depends upon the information needed and the nature of the study area. This decision must be made by a geophysicist who is experienced in both methods, is aware of the geologic information needed by the hydrogeologist, and is also aware of the environment of the study area. The refraction technique has been used more often than the reflection technique for hazardous waste site investigations.

Seismic Refraction Method

Seismic refraction is most commonly used at sites where bedrock is less than 500 feet below the ground surface. Seismic refraction is simply the travel path of a sound wave through an upper medium and along an interface and then back to the surface. A detailed discussion of the seismic refraction technique can be found in Dobrin (1976), Telford, et. al. (1985), and Musgrave (1967).

Advantages: Seismic refraction surveys are more common than reflection surveys for site investigations. The velocities of each layer can be determined from refraction data, and a relatively precise estimate of the depth to different interfaces can be calculated.

Refraction surveys add to depth information inbetween boreholes. Subsurface information can be obtained between boreholes at a fraction of the cost of drilling. Refraction data can be used to determine the depth to the water table or bedrock. In buried valley areas, refraction surveys map the depth to bedrock. The velocity information obtained from a refraction survey can be related to various physical properties of the bedrock. Rock types have certain ranges of velocities and these velocities are not always unique to a particular rock type. However, they can allow a geophysicist to differentiate between certain units, such as shales and granites.

Disadvantages: The seismic refraction method is based on several assumptions. To successfully resolve the subsurface using the refraction method, the conditions of the geologic environment must approximate these assumptions:

- the velocities of the layers increase with depth,
- the velocity contrast between layers is sufficient to resolve the interface, and
- the geometry of the geophones in relation to the refracting layers will permit the detection of thin layers.

These conditions must be met for accurate depth information.

Collecting and interpreting seismic refraction data has several disadvantages. Data collection can be labor intensive. Also, large line lengths are needed; therefore, as a general rule, the distance from the shot, or seismic source, to the first geophone station must be at least three times the desired depth of exploration.

Seismic Reflection Method

The seismic reflection method is not as commonly used on groundwater pollution site investigations as seismic refraction. In the seismic reflection method, a sound wave travels down to a geologic interface and reflects back to the surface. Reflections occur at an interface where there is a change in the acoustic properties of the subsurface material.

Advantages: The seismic reflection method yields information that allows the interpreter to discern between fairly discrete layers, so it is useful for mapping stratigraphy. Reflection data is usually presented in profile form, and depths to interfaces are represented as a function of time. Depth information can be obtained by converting time sections into depth measurements using velocities obtained from seismic refraction data, sonic logs, or

velocity logs. The reflection technique requires much less space than refraction surveys. The long offsets of the seismic source from the geophones, common in refraction surveys, are not required in the reflection method. In some geologic environments, reflection data can yield acceptable depth estimates.

Disadvantages: The major disadvantage to using reflection data is that a precise depth determination cannot be made. Velocities obtained from most reflection data are at least 10% and can be 20% of the true velocities. The interpretation of reflection data requires a qualitative approach. In addition to being more labor intensive, the acquisition of reflection data is more complex than refraction data.

The reflection method places higher requirements on the capabilities of the seismic equipment. Reflection data is commonly used in the petroleum exploration industry and requires a large amount of data processing time and lengthy data collection procedures. Although mainframe computers are often used in the reduction and analysis of large amounts of reflection data, recent advances have allowed for the use of personal computers on small reflection surveys for engineering purposes. In most cases, the data must be recorded digitally or converted to a digital format, to employ various numerical processing operations. The use of high resolution reflection seismic methods relies heavily on the geophysicist, the computer capacity, the data reduction and processing programs, resolution capabilities of the seismograph and geophones, and the ingenuity of the interpreter. Without these capabilities. reflection surveys are recommended.

4.2.5 Ground Penetrating Radar

The ground penetrating radar (GPR) method is used for a variety of civil engineering, groundwater evaluation and hazardous waste site applications. This geophysical method is the most site-specific of all geophysical techniques, providing subsurface information ranging in depth from several tens of meters to only a fraction of a meter. A basic understanding of the function of the GPR instrument, together with a knowledge of the geology and mineralogy of the site, can help determine if GPR will be successful in the site assessment. When possible, the GPR technique should be integrated with other geophysical and

geologic data to provide the most comprehensive site assessment.

The GPR method uses a transmitter that emits pulses of high-frequency electromagnetic waves into the subsurface. The transmitter is either moved slowly across the ground surface or moved at fixed station intervals. The penetrating electromagnetic waves are scattered at points of change in the complex dielectric permittivity, which is a property of the subsurface material dependent primarily upon the bulk density, clay content and water content of the subsurface (Olhoeft, 1984). The electromagnetic energy which is scattered back to the receiving antenna on the surface is recorded as a function of time.

Depth penetration is severely limited by attenuation of the transmitted electromagnetic waves into the ground. Attenuation is caused by the sum of electrical conductivity, dielectric relaxation, and geometric scattering losses in the subsurface. Generally, penetration of radar frequencies is minimized by a shallow water table, an increase in the clay content of the subsurface, and in environments where the electrical resistivity of the subsurface is less than 30 ohm-meters (Olhoeft, 1986). Ground penetrating radar works best in dry sandy soil above the water table. At applicable sites, depth resolution should be between 1 and 10 meters (Benson, 1982).

The analog plot produced by a continuously recording GPR system is analogous to a seismic reflection profile; that is, data is represented as a function of horizontal distance versus time. This representation should not be confused with a geologic cross section which represents data as a function of horizontal distance versus depth. Because very high-frequency electromagnetic waves in the megahertz range are used by radar systems, and time delays are measured in nanoseconds (10° seconds), very high resolution of the subsurface is possible using GPR. This resolution can be as high as 0.1 meter. For depth determinations, it is necessary to correlate the recorded features with actual depth measurements from boreholes or from the results of other geophysical investigations. When properly interpreted, GPR data can optimally resolve changes in soil horizons, fractures, water insoluble contaminants, geological features, manmade buried objects, and hydrologic features such as water table depth and wetting fronts.

Advantages

Most GPR systems can provide a continuous display of data along a traverse which can often be interpreted qualitatively in the field. GPR is capable of providing high resolution data under favorable site conditions. The real-time capability of GPR results in a rapid turnaround, and allows the geophysicist to quickly evaluate subsurface site conditions.

Disadvantages

One of the major limitations of GPR is the site-specific nature of the technique. Another limitation is the cost of site preparation which is necessary prior to the survey. Most GPR units are towed across the ground surface. Ideally, the ground surface should be flat, dry, and clear of any brush or debris. The quality of the data can be degraded by a variety of factors, such as an uneven ground surface or various cultural noise sources. For these reasons, it is mandatory that the site be visited by the project geophysicist before a GPR investigation is proposed. The geophysicist should also evaluate all stratigraphic information available, such as borehole data and information on the depth to water table in the survey area.

4.3 SAMPLE PRESERVATION, CONTAINERS, HANDLING AND STORAGE

This section is not applicable to this SOP.

4.4 INTERFERENCES AND POTENTIAL PROBLEMS

See section 4.2.1 for a discussion of limitations of the magnetic method.

See section 4.2.2 for a discussion of limitations of the electromagnetic method.

See section 4.2.3 for a discussion of limitations of the electrical resistivity method.

See section 4.2.4 for a discussion of limitations of the seismic refraction method and the seismic reflection method. See section 4.2.5 for a discussion of limitations of the ground penetrating radar (GPR) method.

4.5 EQUIPMENT/APPARATUS

4.5.1 Magnetics

- GEM GSM-19G
 magnetometer/gradiometer, EDA OMNI
 IV magnetometer/gradiometer,
 Geonics 856AGX (with built-in datalogger)
 or equivalent
- magnetometer base station
- 300-foot tape measure
- non-ferrous survey stakes (wooden or plastic)

4.5.2 Electromagnetics

- Geonics EM-31, EM-34 or equivalent
- Polycorder datalogger
- Dat 31Q software (data dump software)
- 300-foot tape measure
- survey stakes

4.5.3 Electrical Resistivity

- DC resistivity unit (non-specific)
- 4 electrodes and appropriate cables (length dependent on depth of survey)
- 1 or 2 12-volt car batteries
- 300-foot tape measure

4.5.4 Seismic

- 12- or 24-channel seismograph (Geometrics 2401 or equivalent)
- 30 10Hz to 14Hz geophones (for refraction)
- 30 50Hz or greater geophones (for reflection)
- 300-foot tape measure
- survey stakes
- sledge hammer and metal plate or explosives

4.5.5 Ground Penetrating Radar

- GSSI SIR-8 or equivalent
- 80 Mhz, 100 Mhz or 300 Mhz antenna/receiver pit
- 200-foot cable
- 300-foot tape measure

4.6 REAGENTS

This section is not applicable to this SOP.

4.7 PROCEDURES

Refer to the manufacturer's operating manual for specific procedures relating to operation of the equipment.

4.8 CALCULATIONS

Calculations vary based on the geophysical method employed. Refer to the instrument-specific users manual for specific formulae.

4.9 QUALITY ASSURANCE/ QUALITY CONTROL

The following general quality assurance activities apply to the implementation of these procedures.

- All data must be documented on field data sheets or within site logbooks.
- All instrumentation must be operated in accordance with operating instructions as supplied by the manufacturer, unless otherwise specified in the work plan. Equipment checkout and calibration activities must occur prior to sampling/operation, and they must be documented.

Method-specific quality assurance procedures may be found in the user's manual.

4.10 DATA VALIDATION

Evaluate data as per the criteria established in section 4.9 above.

4.11 HEALTH AND SAFETY

When working with potentially hazardous materials, follow U.S. EPA, OSHA and specific health and safety procedures.

APPENDIX A

Figures

Figure 1: Sampling Augers
SOP #2012

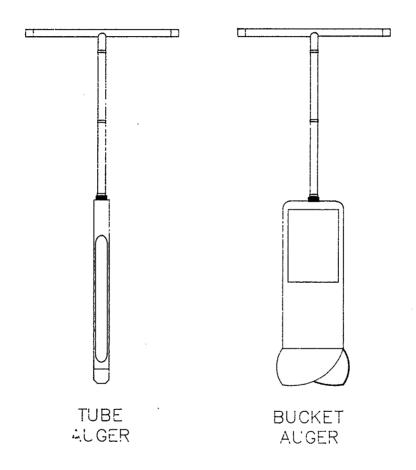


Figure 2: Sampling Trier SOP #2012

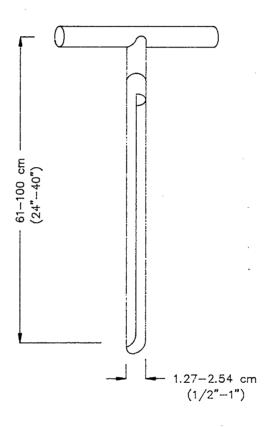
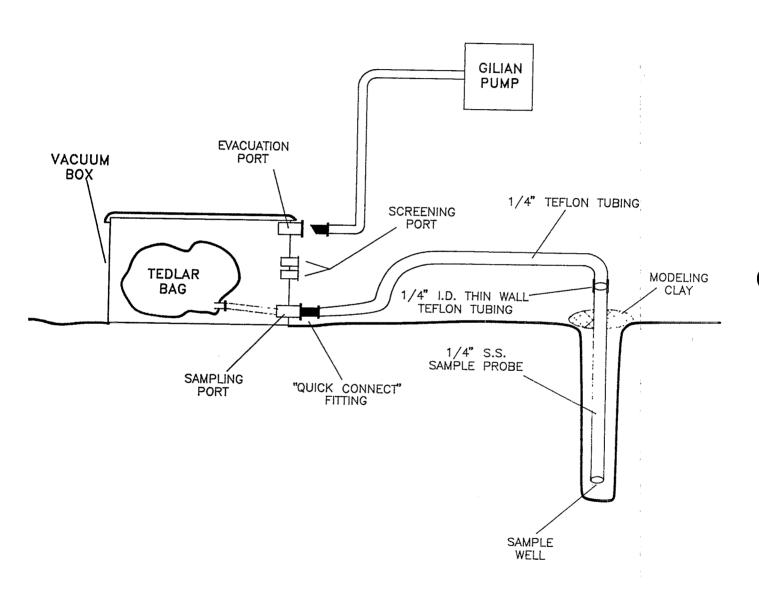


Figure 3: Sampling Train Schematic SOP #2149



APPENDIX B

HNU Field Protocol

HNU Field Protocol SOP #2149

Startup Procedure

- 1. Before attaching the probe, check the function switch on the control panel to ensure that it is in the "off" position. Attach the probe by plugging it into the interface on the top of the readout module. Use care in aligning the prongs in the probe cord with the socket: do not force it.
- 2. Turn the function switch to the battery check position. The needle on the meter should read within or above the green area on the scale. If not, recharge the battery. If the red indicator light comes on, the battery needs recharging.
- 3. Turn the function switch to any range setting. For no more than 2 to 3 seconds, look into the end of the probe to see if the lamp is on. If it is on, you will see a purple glow. Do not stare into the probe any longer than three seconds. Long term exposure to UV light can damage the eyes. Also, listen for the hum of the fan motor.
- 4. To zero the instrument, turn the function switch to the standby position and rotate the zero adjustment until the meter reads zero. A calibration gas is not needed since this is an electronic zero adjustment. If the span adjustment setting is changed after the zero is set, the zero should be rechecked and adjusted, if necessary. Wait 15 to 20 seconds to ensure that the zero reading is stable. If necessary, readjust the zero.

Operational Check

- 1. Follow the startup procedure.
- 2. With the instrument set on the 0-20 range, hold a solvent-based Magic Marker near the probe tip. If the meter deflects upscale, the instrument is working.

Field Calibration Procedure

1. Follow the startup procedure and the operational check.

- 2. Set the function switch to the range setting for the concentration of the calibration gas.
- 3. Attach a regulator (HNU 101-351) to a disposable cylinder of isobutylene gas. Connect the regulator to the probe of the HNU with a piece of clean Tygon tubing. Turn the valve on the regulator to the "on" position.
- 4. After 15 seconds, adjust the span dial until the meter reading equals the concentration of the calibration gas used. The calibration gas is usually 100 ppm of isobutylene in zero air. The cylinders are marked in benzene equivalents for the 10.2 eV probe (approximately 55 ppm benzene equivalent) and for the 11.7 eV probe (approximately 65 ppm benzene equivalent). Be careful to unlock the span dial before adjusting it. If the span has to be set below 3.0 calibration, the lamp and ion chamber should be inspected and cleaned as appropriate. For cleaning of the 11.7 eV probe, only use an electronic-grade, oil-free freon or similar water-free, grease-free solvent.
- 5. Record in the field log: the instrument ID # (EPA decal or serial number if the instrument is a rental); the initial and final span settings; the date and time; concentration and type of calibration used; and the name of the person who calibrated the instrument.

Operation

- 1. Follow the startup procedure, operational check, and calibration check.
- 2. Set the function switch to the appropriate range. If the concentration of gases or vapors is unknown, set the function switch to the 0-20 ppm range. Adjust it as necessary.
- 3. While taking care not to permit the HNU to be exposed to excessive moisture, dirt, or contamination, monitor the work activity as specified in the site health and safety plan.
- 4. When the activity is completed or at the end of the day, carefully clean the outside of the HNU with a damp disposable towel to remove any

visible dirt. Return the HNU to a secure area and place on charge.

5. With the exception of the probe's inlet and exhaust, the HNU can be wrapped in clear

plastic to prevent it from becoming contaminated and to prevent water from getting inside in the event of precipitation.

; ¥ Ī ! 1 .

References

SOPs #2006, 2012, 2149

- American Standards for Testing and Materials. 1988. Standard Method for Preparing Test and Split-Barrel Sampling of Soils: Annual Book of ASTM Standards. Section 4, Volume 4.08. ASTM D1586-84.
- Barth, D.S. and B.J. Mason. 1984. Soil Sampling Quality Assurance User's Guide. EPA/600/4-84/043.
- de Vera, E.R., B.P. Simmons, R.D. Stephen, and D.L. Storm. 1980. Samplers and Sampling Procedures for Hazardous Waste Streams. EPA/600/2-80/018.
- Gilian Instrument Corp. 1983. Instruction Manual for Hi Flow Sampler: HFS 113, HFS 113 T, HFS 113 U, HFS 113 UT.
- HNU Systems, Inc. 1975. Instruction Manual for Model PI 101 Photoionization Analyzer.
- Mason, B.J. 1983. Preparation of Soil Sampling Protocol: Technique and Strategies. EPA/600/4-83/020.
- National Institute for Occupational Safety and Health. October, 1985. Occupational Safety and Health Guidance Manual for Hazardous Waste Site Activities. NIOSH/OSHA/USCG/EPA.
- New Jersey Department of Environmental Protection. February, 1988. Field Sampling Procedures Manual.
- Roy F. Weston, Inc. 1987. Weston Instrumentation Manual, Volume I.
- U.S. Environmental Protection Agency. December, 1984. Characterization of Hazardous Waste Sites A Methods Manual: Volume II, Available Sampling Methods, 2nd Edition. EPA/600/4-84/076.
- U.S. Environmental Protection Agency. April 1, 1986. Engineering Support Branch Standard Operating Procedures and Quality Assurance Manual. U.S. EPA Region IV.
- U.S. Environmental Protection Agency. 1987. A Compendium of Superfund Field Operations Methods. EPA/540/P-87/001. Office of Emergency and Remedial Response. Washington, D.C. 20460.

SOP #2159

<u>Magnetics</u>

- Breiner, S. 1973. Applications Manual for Portable Magnetometers: EG&G GeoMetrics. Sunnyvale, California.
- Fowler, J. and D. Pasicznyk. February, 1985. Magnetic Survey Methods Used in the Initial Assessment of a Waste Disposal Site: National Water Well Association Conference on Surface and Borehole Geophysics.

- Lilley, F. 1968. Optimum Direction of Survey Lines. Geophysics 33(2): 329-336.
- Nettleton, L.L. 1976. Elementary Gravity and Magnetics for Geologists and Seismologists: Society of Exploration Geophysicists. Monograph Series Number 1.
- Redford, M.S. 1964. Magnetic Anomalies over Thin Sheets. Geophysics 29(4): 532-536.
- Redford, M.S. 1964. Airborne Magnetometer Surveys for Petroleum Exploration: Aero Service Corporation. Houston, Texas.
- Vacquier, V. and others. 1951. Interpretation of Aeromagnetic Maps: Geological Society of America. Memoir Number 47.

Electromagnetics

- Duran, P.B. 1982. The Use of Electromagnetic Conductivity Techniques in the Delineation of Groundwater Pollution Plumes: unpublished master's thesis, Boston University.
- Grant, F.S. and G.F. West. 1965. Interpretation Theory in Applied Geophysics. McGraw-Hill Book Company, New York, New York.
- Greenhouse, J.P., and D.D. Slaine. 1983. The Use of Reconnaissance Electromagnetic Methods to Map Contaminant Migration. Ground Water Monitoring Review 3(2).
- Keller, G.V. and F.C. Frischknecht. 1966. *Electrical Methods in Geophysical Prospecting*. Pergamon Press, Long Island City, New York.
- McNeill, J.D. 1980. Electromagnetic Terrain Conductivity Measurements at Low Induction Numbers. Technical Note TN-6, Geonics Limited. Mississauga, Ontario, Canada.
- McNeill, J.D. 1980. EM34-3 Survey Interpretation Techniques. Technical Note TN-8, Geonics Limited. Mississauga, Ontario, Canada.
- McNeill, J.D. 1980. Electrical Conductivity of Soils and Rocks. Technical Note TN-5, Geonics Limited. Mississauga, Ontario, Canada.
- McNeill, J.D. and M. Bosnar. 1986. Surface and Borehole Electro-Magnetic Groundwater Contamination Surveys, Pittman Lateral Transect, Nevada: Technical Note TN-22, Geonics Limited. Mississauga, Ontario, Canada.
- Stewart, M.T. 1982. Evaluation of Electromagnetic Methods for Rapid Mapping of Salt Water Interfaces in Coastal Aquifers. *Ground Water* 20.
- Telford, W.M., L.P. Geldart, R.E. Sheriff, and D.A. Keys. 1977. Applied Geophysics. Cambridge University Press. New York, New York.

Electrical Resistivity

Bisdorf, R.J. 1985. Electrical Techniques for Engineering Applications. Bulletin of the Association of Engineering Geologists 22(4).

- Grant, F.S. and G.F. West. 1965. Interpretation Theory in Applied Geophysics. McGraw-Hill Book Company, New York, New York.
- Keller, G.V. and F.C. Frischnecht. 1966. *Electrical Methods in Geophysical Prospecting*. Pergamon Press, Long Island City, New York.
- Kelly, W.E. and R.K. Frohlich. 1985. Relations between Aquifer Electrical and Hydraulic Properties. Ground Water 23:2.
- Stollar, R. and P. Roux. 1975. Earth Resistivity Surveys -- A Method for Defining ^Groundwater Contamination. *Ground Water* 13.
- Sumner, J.S. 1976. Principles of Induced Polarization for Geophysical Exploration. Elsevier Scientific Publishing, New York, New York.
- Telford, W.M., L.P. Geldart, R.E. Sheriff, and D.A. Keys. 1977. Applied Geophysics. Cambridge University Press, New York, New York.
- Urish, D.W. 1983. The Practical Application of Surface Electrical Resistivity to Detection of Ground Water Pollution. *Ground Water* 21.
- Van Nostrand, R.E., and L.K. Cook. 1966. Interpretation of Resistivity Data: U.S. Geological Survey Professional Paper 499, Washington, D.C.
- Zohdy, A.A.R. 1975. Automatic Interpretation of Schlumberger Sounding Curves Uusing Modified Dar Zarrouk Functions. U.S. Geological Survey Bulletin 1313-E, Denver, Colorado.

Seismic

- Coffeen, J.A. 1978. Seismic Exploration Fundamentals. PennWell Publishing, Tulsa, Oklahoma.
- Dobrin, M.B. 1976. Introduction to Geophysical Prospecting; 3rd ed. McGraw-Hill, New York, New York.
- Griffiths, D.H. and R.E. King. 1981. Applied Geophysics for Geologists and Engineers. Second edition. Pergamon Press, Oxford, England.
- Miller, R.D., S.E. Pullan, J.S. Waldner, and F.P. Haeni. 1986. Field Comparison of Shallow Seismic Sources. *Geophysics* 51(11): 2067-92.
- Musgrave, A.W. 1967. Seismic Refraction Prospecting. The Society of Exploration Geophysicists. Tulsa, Oklahoma.
- Telford, W.M., L.P. Geldant, R.E. Sheriff, and D.A. Keys. 1985. Applied Geophysics. Cambridge University Press, Cambridge, England.

Ground Penetrating Radar

Benson, R.C., R.A. Glaccum, and M.R. Noel. 1982. Geophysical Techniques for Sensing Buried Wastes and Waste Migrations. Technos Inc. Miami, Florida. 236 pp.

Olehoft, G.R. 1984. Applications and Limitations of Ground Penetrating Radar: Expanded Abstracts, Society of Exploration Geophysicists. 54th Annual Meeting: December 2-6, 1984. Atlanta, Georgia. 147-148.